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#### Deltronics (The Netherlands) B.V.

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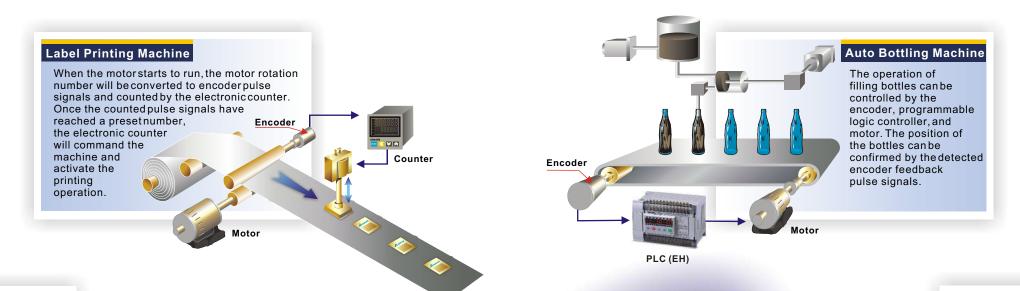
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<sup>\*</sup>We reserve the right to change the information in this catalogue without prior notice

# **Rotary Optical Encoder**

# **Various Applications**





#### Use a sensor to generate pulse signals that is processed by the Rotary Optical Encoder for counting. When the counted pulse signals have

**Detecting Machine** 

Encoder reached a preset number, the object will be detected and its size will be verified if correct or not

#### Elevator

Rotary Optical Encoder is connected to the motor directly. When the elevator moves, the motor rotation numbers will be converted to encoder pulse signals. Then, the moving speed of the elevator can be known by the detected encoder feedback pulse signals.

Rotary Optical Encoder is a sensor, which converts rotary motion or position to electronic pulse numbers for phase change, speed and position detection. It is also used to detect the speed, position, angle, distance and counts information relating to mechanical machine.

Major applications include main hoist of crane (crane control), elevator, industry sewing machine, textile machine, storage equipment, medical treatment related machine, and servo motor. Therefore, Rotary Optical Encoder is a very important device in industrial automation field.

## Fixed Length Cutting Machine

the motor rotation number will be converted to encoder pulse signals and counted by the electronic counter. Once the counted pulse signals have reached a preset number, the electronic counter will command the cutting machine to cut the material in the same and fixed length.

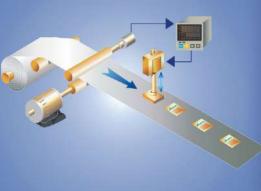
When the motor starts to run,

#### Elevator Door

Rotary Optical Encoder is connected to the motor directly. When the motor starts to run, the motor rotation number will be converted to encoder pulse signals. The Rotary Optical Encoder is used to detect and confirm the position and speed of the elevator



# **Rotary Optical Encoder**



# **Ordering Information**



# **Model Name Explanation**

ES5-05CN8942F is an incremental encoder, shaft type is solid shaft, outer diameter is 50mm, resolution can reach 500PPR, output form is open collector, signal output is A, B & Z (ungated), shaft/bore diameter is 8mm, input voltage is  $7\sim24$ VDC and operation environment is IP40. It means ES5-05CN8942F this product has protection against solid foreign objects of 1.0 mm in diameter and greater but does not have waterproof protection. Also, it is suitable for the use within -10°C  $\sim70$ °C operating temperature. Besides, the cable length of ES5-05CN8942F is 2000mm and mechanism code is F (F: Flange).

#### <u>E S 5 - 0 5 C N 8 9 4 2 F</u> Example

1 2 3 - 4 5 6 7 8 9 10 11 Code Order

## 1.Product Type

- E: Incremental Encoder
- A: Absolute Encoder
- C: CNC Incremental Encoder
- M: Incremental Encoder with commutation UVW (for Servo Motor)

# 2.Shaft Type

- S: Solid Shaft
- H: Hollow Shaft
- T: Through Hole Shaft

#### 3.Outer Diameter / Frame Size

- 3:36.6mm 4:38.7mm 5:50mm A:100mm
- 7:68mm

# 4.Resolution ES/EH/ET (PPR): 01:100; 02:200; 0B:256; 03:300; 0C:360; 04:400; 05:500; 06:600; 10:1000; 11:1024; 12:1200; 20:2000; 25:2500; 36:3600; 50:5000 AS/AH (BIT): 05;06;07;08;09;10;11;12 MH/MT (PPR): 25:2500 CS(PPR): 11:1024

#### 5.Output Form

V: Voltage Output C: Open Collector
L: Line Driver P: Push Pull

#### **6.Signal Output**

#### ES/EH/ET:

- A: A(without Z signaloutput)
- B: A& B (without Z signal output)
- G: A, B & Z (Gated with A&B)
- N: A, B & Z(Ungated)
- U: A, B & Z(Ungated, active low)
- V: A, B & Z (Gated with A&B, active low)

#### AS/AH:

B: Binary code G: Gray code

#### MH/MT

- F: 14 cores, A, B & Z and U, V, W output simultaneously
- N: 8 cores, A, B & Z and U, V, W do not output simultaneously

#### 7.Shaft/Bore Diameter

4: 4mm 5: 5mm 6: 6mm 8: 8mm M: 30mm Q: 1/4 inch T: 9mm with Taper 1:10 R:15mm

## 8.Input Voltage

5:5VDC; 8:5~12VDC; 9:7~24VDC

#### 9. Operating Environment

- 1: IP40 & 60°C; 4: IP40 & 70°C; 6: IP65 & 70°C;
- C: IP30 & 85°C; H: IP55 & 70 °C

#### 10.Cable Length

- 1:1000 mm; 2:2000 mm; 3:3000 mm;
- 5:500 mm; 7:170 mm; A: 300 mm;
- M: Military Connector

#### 11.Suffix Code

- 0: UVW 10 poles; 4: UVW 4 poles; 6: UVW 6 poles;
- 8: UVW 8 poles; F: Flange

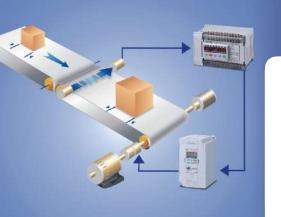
IP (Ingress Protection) is a coding system which is used to indicate the environmental protection of enclosures around the electrical equipment. The environmental protection includes the degree of protection from ingress of solid foreign objects, ingress of water and mechanical impacts. IP code normally has two numbers.

The first number indicates the degree of protection against solid foreign objects and the degree that persons are protected against hazardous parts or harmful deposit.

The second number indicates the degree of protection against water. The number is higher, the protection is better.

For example, IP Rating IP 65, 6 describes the level of protection from totally protected against dust and 5 describes the level of protection against low pressure jetting water from all directions.



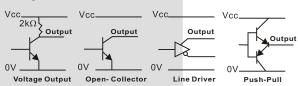


# **Specifications**

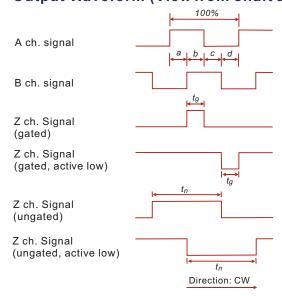
# **ES/EH/ET Series**

Wire Color	Brown	Blue	Black	Black /Red	White	White /Red	Orange	Orange /Red
Function	Vcc	0V	Α	Ā	В	B	Z	Z
Voltage Output	0	0	0	-	0	-	0	-
Open Collector	0	0	0	-	0	-	0	-
Line Driver	0	0	0	0	0	0	0	0
Push Pull	0	0	0	-	0	-	0	-

#### **Output Circuit**



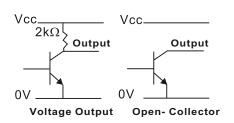
#### Output Waveform (View from shaft end)



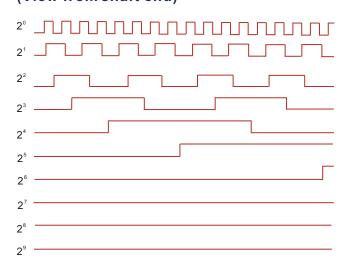
# **AS/AH Series**

Wire Color	Function	Wire Color	Function
Red	Vcc	Blue	<b>2</b> <sup>4</sup>
Black	0V	Purple	<b>2</b> <sup>5</sup>
Brown	<b>2</b> °	Gray	2 <sup>6</sup>
Orange	2¹	White	27
Yellow	<b>2</b> <sup>2</sup>	Pink	2 <sup>8</sup>
Green	<b>2</b> ³	Light Blue	2 9

#### **Output Circuit**



#### **Output Waveform** (View from shaft end)



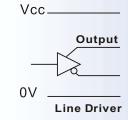
# MH4/MT4 Series

Wire Color	Function	Wire Color	Function
Black	Α	Yellow	U
Black/Red	Ā	Yellow/Red	Ū
White	В	Green	V
White/Red	B	Green/Red	⊽
Orange	Z	Pink	W
Orange/Red	₹	Pink/Red	$\overline{w}$
Brown	DC+5V	Blue	0V

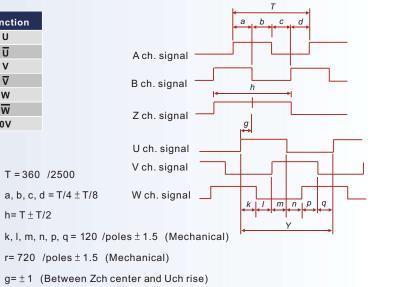
T = 360 /2500

 $h=T\pm T/2$ 

#### **Output Circuit**



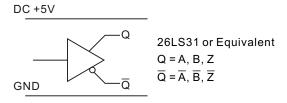
## **Output Waveform** (CCW rotation, view from shaft end)



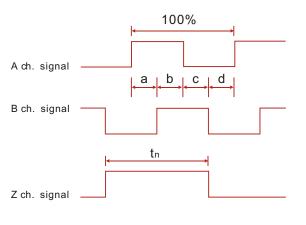
# **CS Series**

Function	PIN	Function	PIN
Vcc	Н	ov	K
Α	Α	Ā	N
В	С	B	R
Z	В	Z	Р
Shielding	T		

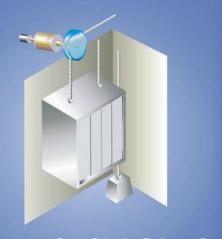
#### **Output Circuit**



#### **Output Waveform** (CW rotation, view from shaft end)



 $12.5\% \le a,b,c,d \le 37.5\%$ ;  $50\% \le tn \le 150\%$ 



# **Incremental Encoder**

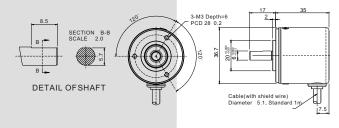
# Solid Shaft Outer Diameter 36.6mm



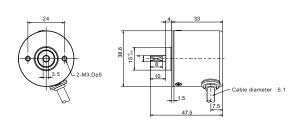
		Series			E	S3 Series			
	Model Name		ES35XX	ES3.	8XX	ES39XX			
	Rated Voltage		5±5%V 5-5%~12+5%V		12+5%V	7-5%~24+5%V			
	Output Type		Open Collector	Voltage Output	Push Pull	Line Driver			
	Sink Current		20 mA		20 mA	20mA			
	ions	Source (	Current			20 mA	26C31or equivalent		
	Electrical Specifications	Max. Lo Power \		DC30V					
	pec	Output Signal			A,B,Z		$A, \overline{A}, B, \overline{B}, Z, \overline{Z}$		
	al S	Output VH		>(V <sub>in</sub> -2V)		≧(Vcc-2V)			
N	Voltage VL		≦500mV						
	Ш	Current Max. R Cable I Output Cable I Cross S	Consuesponse Diamete Phase Sength: Sections	mption: 100mAM e Frequency: 300 r: 5.1mm Difference: Outpu 500 / 1000 / 2000 al Area: 0.18mm²	ference:Output phase difference90 + zero pointsignal 0 / 1000 / 2000±20mm				
	Mechanical Specifications	Max. Speed of Main Shaft: 6000rpm Starting Torque: 2.0 N-mm Typ. / 5.0 N-mm Typ. (IP65) Moment of Inertia: 0.3 kg mm² Typ. Outer Diameter: 36.6mm Height: 33mm (S4) / 35mm(S6) / 50.2mm(IP65) Weight: <70g / <120g (IP65) Shaft Diameter: 4mm / 6mm Max. Shaft Load: Thrust: 15 N/ Radial: 30N (10 mm from mounting surface) Wire Color: Vcc: Brown, 0V: Blue, A: Black, Ā: Black / Red, B: White, B: White / Red, Z: Orange, Z: Orange / Red							
	nvironmental pecifications			perature: -10°C~ erature: -25°C~85 at 6ms 2200Hz at 5G's gree: IP40 /IP65					

# **Dimensions**

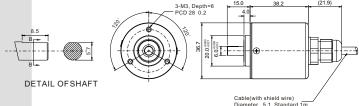
#### Shaft Diameter 6mm



#### Shaft Diameter 4mm



## Shaft Diameter 6mm (IP65 Type)



# Solid Shaft Outer Diameter 50mm



	Series	;	ES5 series				
Model Name		ES55XX	ES58XX		ES59XX		
	Rated Voltage		5±5%V	5-5%~1	2+5%V	7-5%~24+5%V	
	Output Type		Open Collector	Voltage Output	Push Pull	Line Driver	
Electrical Specifications	Sink Current		20 mA		20 mA	20mA	
	Source Current				20 mA	26C31or equivalent	
	Max. Load Power Voltage		DC30V				
pec	Output	Signal	A,B,Z		$A, \overline{A}, B, \overline{B}, Z, \overline{Z}$		
al S	Output	VH	>(V <sub>in</sub> -2V)		≧(Vcc-2V)		
tric	Voltage	VL			≦500mV		
Elec	Curren Max. R Cable	t Consu espons Diamete	ution: 100 to 250 mption: 100mAM e Frequency: 300 rr: 5.1mm Difference: Outpu	lax. kHz Max.	ce90 + zero poiı	ntsignal	

Cable Length: 500/1000/2000 ± 20mm

Cross Sectional Area: 0.18mm<sup>2</sup>

Signal Characteristic: Rise Time  $1\mu$ s Typ.; Fall Time  $1\mu$ s Typ. Max. Speed of Main Shaft: 6000rpm Starting Torque: 4.0 N-mm Typ. / 6.0 N-mm Typ. (IP65) Moment of Inertia: 0.8 kg mm² Typ.

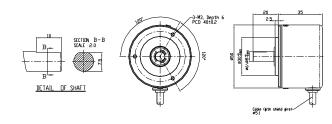
Outer Diameter: 50mm
Height: 35mm /57mm(IP65)
Weight: <130g /<145g (IP65)(All provided without Flange)
Shaft Diameter: 5mm /6mm / 8mm
Max. Shaft Load: Thrust: 30N /Radial: 50N (10 mm from mounting surface)

Wire Color: Vcc: Brown, 0V: Blue, A: Black, A: Black / Red, B: White, B: White / Red, Z: Orange, Z: Orange / Red

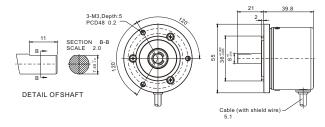
Operating Temperature: -10°C~70°C, 95%RH (Non-condensing, Non-freezing) Storage Temperature: -25°C~85°C (Non-condensing, Non-freezing) Shock: 100G's at6ms Vibration: 10 to 200Hz at 5G's Protection Degree: IP40 /IP65

# **Dimensions**

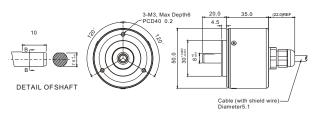
#### Shaft Diameter 6mm / 8mm



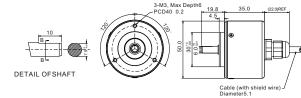
# Shaft Diameter 8mm (Flange Type)



#### Shaft Diameter 8mm (IP65 Type)



#### Shaft Diameter 6mm (IP65 Type)





# **Incremental Encoder**

# Hollow Shaft Outer Diameter 36.6mm

# EH3



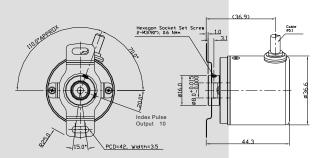
1	Series				E	H3 Series	
	N	lodel Na		EH35XX	EH3		EH39XX
		Rated Voltage		5±5%V 5-5%~12+5%V		7-5%~24+5%V	
	Output Type		Open Collector Voltage Output Push Pu		Push Pull	Line Driver	
		Sink Current		ink Current 20 mA 20 mA		20mA	
	ions	Source (	Current		20 mA		26C31or equivalent
	Electrical Specifications	Max. Lo Power \		DC30V			
	pec	Output	Signal		A,B,Z	$A, \overline{A}, B, \overline{B}, Z, \overline{Z}$	
	als	Output	VH	>(V <sub>in</sub> -2V) ≧(Vcc-2V)			
	tric	Voltage	VL	≦500mV			
	Ele	Curren Max. R Cable I Output Cable I Cross S	t Consu esponse Diamete Phase I Length : Sections	ution: 100 to 2500 mption: 100 mAM e Frequency: 3000 ir: 5.1 mm Difference: Outpu 500/1000/2000 dal Area: 0.18 mm² teristic: Rise Tim	ax. kHz Max. t phase difference 20mm		
	Signal Characteristic: Rise Time 1 \( \mu \)s Typ.; Fall Time 1 \( \mu \)s Typ.  Max. Speed of Main Shaft: 6000rpm Starting Torque: 4.0 N-mm Typ. / 6.0 N-mm Typ. (IP65) Moment of Inertia: 1.5 kg mm² Typ. Outer Diameter: 36.6mm Height: 44.3mm / 70.2mm(IP65) Weight: <85g / <130g (IP65) Bore Diameter: 8mm Max. Shaft Load: Thrust: 15N /Radial: 30N (10 mm from shaftend) Wire Color: Vcc: Brown, 0V: Blue, A: Black, \( \bar{A} \): Black / Red, B: White / \( \bar{Z} \): Orange / Red						

Operating Temperature: -10°C~70°C, 95%RH (Non-condensing, Non-freezing) Storage Temperature: -25°C~85°C (Non-condensing, Non-freezing) Shock: 100G's at6ms Vibration: 10 to 200Hz at 5G's

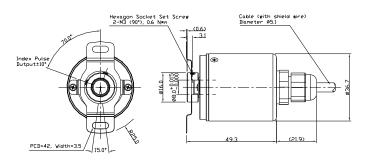
Protection Degree: IP40 /IP65

# **Dimensions**

#### Bore Diameter 8mm



#### Bore Diameter 8mm (IP65 Type)



# Hollow Shaft Outer Diameter 38.7mm

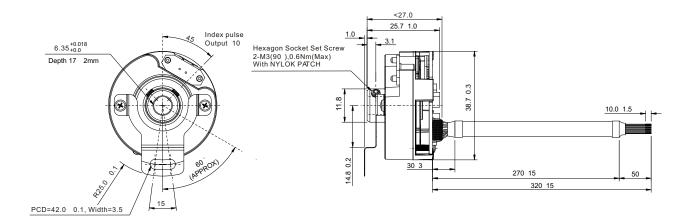
# EH4

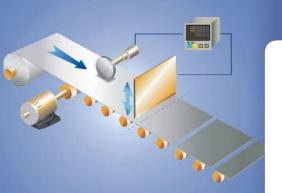


Series				E	H4 Series		
	Model N	ame	EH45XX	EH4	.8XX	EH49XX	
	Rated V	'oltage	5±5%V	5-5%~1	2+5%V	7-5%~24+5%V	
	Output	Туре	Open Collector	Voltage Output	Push Pull	Line Driver	
	Sink C	urrent	20 mA		20 mA	20mA	
ons	Source (	Current			20 mA	26C31or equivalent	
Electrical Specifications	Max. Lo Power \		DC30V				
oe ci	Output	Signal		A,B,Z		$A, \overline{A}, B, \overline{B}, Z, \overline{Z}$	
S	Output VH		>(V <sub>in</sub> -2V)		≧(Vcc-2V)		
ü	Voltage						
		Cross Sectional Area: 0.18mm² Signal Characteristic: RiseTime 1 µs Typ.; Fall Time 1 µs Typ.					
Mechanical Specifications	Max. S Starting Momen Outer E Height: Weight Bore Di Max. S	Sectional Charact Charact Peed of Torque It of Iner Diamete 26.7mr : <85g Itameter The Itameter Itamet	eristic: RiseTime Main Shaft: 6000 a: 4.0 N-mm Typ . tia: 1.2 kg mm² T r: 38.7mm n c: 6.35mm ad: Thrust: 30N /F	rpm 「yp. Radial: 50N (10m	m from shaftend		
			c:Brown, 0V:Blue Orange, Z:Orang		ack / Red, B: Wh	ite, B: White / Red,	
nvironmental pecifications	Operati Storage Shock: Vibration Protect	e Tempe 100G's on: 10 to	perature: -10°C~8 rature: -25°C~10 at6ms 200Hzat 5G's ree: IP30				

# **Dimensions**

#### Bore Diameter 6.35mm





# **Incremental Encoder**

# Hollow Shaft Outer Diameter 50mm

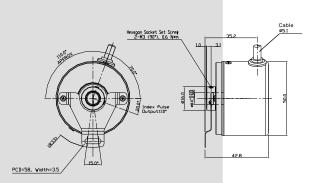
# EH5



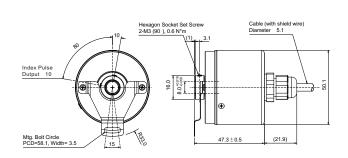
	Series			E	H5 Series		
Model Name		EH55XX EH58XX		EH59XX			
Rated Voltag		oltage	5±5%V	5-5%~12+5%V		7-5%~24+5%V	
	Output	Туре	Open Collector	Open Collector Voltage Output Push Pull		Line Driver	
<b>"</b>	Sink C	Sink Current 20		20 mA		20mA	
ioi	Source (	Current			20 mA	26C31or equivalent	
Electrical Specifications	Max. Load Power Voltage		DC30V				
bec	Output Signal			A,B,Z		$A, \overline{A}, B, \overline{B}, Z, \overline{Z}$	
Output VH		VH	>(V <sub>in</sub> -2V)	$>(V_{in}-2V)$ $\geq (Vcc-2V)$			
tric	Voltage	VL	≦500mV				
	Max. Response Frequency: 300kHz Max. Cable Diameter: 5.1mm  Output Phase Difference: Output phase difference90 + zero pointsignal Cable Length: 500/1000/2000±20mm  Cross Sectional Area: 0.18mm²  Signal Characteristic: RiseTime 1 \( \mu \) s Typ.; Fall Time 1 \( \mu \) s Typ.						
Mechanical Specifications	Wire Color: Vcc:Brown, UV:Blue, A:Black, A:Black / Red, B: White, B:White / Red,						
orifications	Z: Orange, Z: Orange / Red						

# **Dimensions**

#### Bore Diameter 8mm



# Bore Diameter 8mm (IP65 Type)



# Through Hole Shaft Outer Diameter 100mm

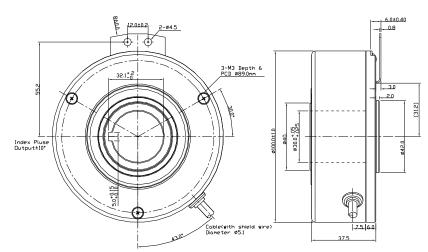
# ETA

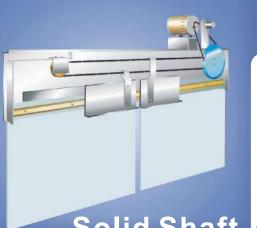


	Serie	s		E	TA Series	
	Model Name		ETA5XX ETA8XX		вхх	ETA9XX
	Rated V	oltage	5±5%V 5-5%~12+5%V		+5%V	7-5%~24+5%V
	Output	Туре	Open Collector	Voltage Output	Push Pull	Line Driver
	Sink C	urrent	20 mA		20 mA	20mA 26C31or equivalent
ons	Source (	Current			20 mA	2003 for equivalent
Electrical Specifications	Max. Lo Power \		DC30V			
pec	Output Signal			A,B,Z		$A, \overline{A}, B, \overline{B}, Z, \overline{Z}$
al S	Output VH		>(V <sub>in</sub> -2V)		≧(Vcc-2V)	
tric	Voltage	VL	≦500mV			
	Output Phase Difference:Output phase difference90 + zero pointsignal Cable Length:500/1000/2000±20mm Cross Sectional Area: 0.18mm <sup>2</sup> Signal Characteristic: RiseTime 1 \mu s Typ.; Fall Time 1 \mu s Typ.					
Mechanical Specifications	Max. Speed of Main Shaft: 3000rpm Starting Torque: 60 N-mm Typ. Moment of Inertia: 1.6 kg mm² Typ. Outer Diameter: 100mm Height: 37.5mm Weight: <1000g Bore Diameter: 30mm Max. Shaft Load: Thrust: 30N /Radial: 50N (10mm from mounting surface) Wire Color: Vcc: Brown, _0V: Blue, _A: Black / Red, B: White, _B: White / Red,					
vironmental ecifications	Z: Orange, \(\overline{Z}\): Orange/ Red  Operating Temperature: -10°C~70°C, 95%RH (Non-condensing, Non-freezing)  Storage Temperature: -25°C~85°C (Non-condensing, Non-freezing)  Shock: 100G's at6ms  Vibration: 10 to 200Hz at 5G's  Protection Degree: IP40					

# **Dimensions**

## Bore Diameter 30mm





# **Absolute Encoder**

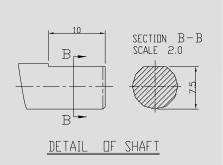
# Solid Shaft Outer Diameter 50mm

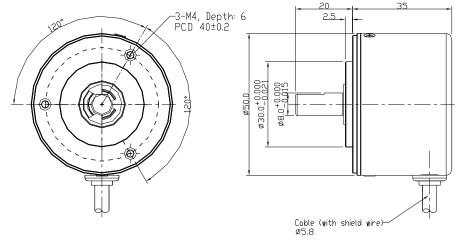


		Serie		ASS S	Series			
	Model Name			AS55XX	AS58XX			
		Rated V	oltage	5±5%V	5-5%~12+5%V			
		Output Type		Open Collector	Voltage Output			
		Sink C	urrent	20 mA				
	ions	Source C	Current					
	ficati	Max. Lo Power V		DC15V				
	oeci	Output	-	Gray	Code			
	Source Current  Max. Load Power Voltage Output Signal  Output VH Voltage VL  Encoder Reso		VH	>(V <sub>in</sub> -2V)	≧(Vcc-2V)			
1			VL	≦500mV				
		Current Max. Ro Cable D Cable L Cross S	t Consu esponse Diamete ength:	ution: 5bit to 10bit mption: 200mAMax. e Frequency: 20kHz Max. r: 5.8mm 1000±20mm al Area: 0.18mm² eristic: RiseTime 1 \mu s Typ.; Fall Time 1 \mu s Typ.				
	Mechanical Specifications	Max. Speed of Main Shaft: 3000rpm Starting Torque: 4.0 N-mm Typ. Moment of Inertia: 0.8 kg mm² Typ. Outer Diameter: 50mm Height: 35mm Weight: <130g Shaft Diameter: 8mm Max. Shaft Load: Thrust: 30N /Radial: 50N (10 mm from mounting surface) Wire Color: Vcc: Red, 0V: Black, 2º: Brown, 2¹: Orange, 2²: Yellow, 2³: Green, 2⁴: Blu 2⁵: Purple, 2⁰: Gray, 2¹: White, 2³: Pink, 2³: Light Blue						
2°: Purple, 2°: Gray, 2′: White, 2°: Pink, 2°: Light Blue  Operating Temperature: -10°C~60°C, 95%RH (Non-condensing, No Storage Temperature: -25°C~75°C (Non-condensing, Non-freezing) Shock: 100G's at 6ms Vibration: 10 to 200Hz at 5G's Protection Degree: IP40								

# **Dimensions**

#### Shaft Diameter 8mm





# Hollow Shaft Outer Diameter 50mm

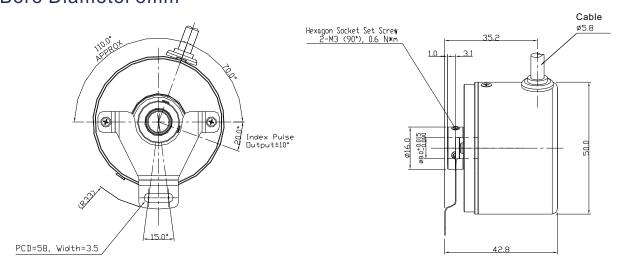


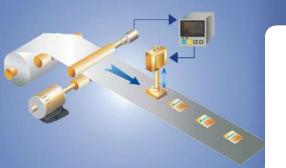


	0		ΔΗ5.5	Series			
	Serie Model N		AH55XX	AH58XX			
	Rated \	/oltage	5±5%V	5-5%~12+5%V			
	Output	Туре	Open Collector	Voltage Output			
<b>"</b>	Sink C	Current	20 mA				
ations	Source	Current					
Electrical Specifications	Max. Le Power	oad Voltage	DC15V				
Spe	Output	Signal	Gray Code				
ical	Output	VH	>(V <sub>in</sub> -2V)	≧(Vcc-2V)			
ectr	Voltage						
	Cable Diameter : $5.8 \text{mm}$ Cable Length: $1000 \pm 20 \text{mm}$ Cross Sectional Area: $0.18 \text{mm}^2$ Signal Characteristic: Rise Time $1 \mu$ s Typ.; Fall Time $1 \mu$ s Typ.						
Mechanical Specifications	Max. Speed of Main Shaft: 3000rpm Starting Torque: 4.0 N-mm Typ. Moment of Inertia: 0.8 kg mm² Typ. Outer Diameter: 50mm Height: 35mm Weight: <135g Bore Diameter: 8mm Max. Shaft Load: Thrust: 30N / Radial: 50N (10 mm from mounting surface) Wire Color: Vcc: Red, 0V: Black , 2º: Brown, 2¹: Orange, 2²: Yellow, 2²: Green, 2⁴: B  2⁵: Purple, 2⁵: Gray, 2⁻: White, 2⁵: Pink, 2⁰: Light Blue						
nvironmental pecifications	Opera Storag Shock	e Tempe	perature: -10°C~60°C, 95%RH (Non-cerature: -25°C~75°C (Non-condensing,				

# **Dimensions**

#### Bore Diameter 8mm





# Commutation Encoder (For Servo Motor)



# Hollow Shaft Outer Diameter 40.9mm

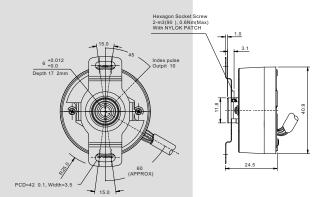
# MH4



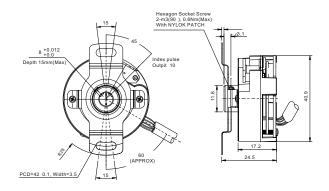
		Series		MH4 Series		
Ī		Model N	ame	MH45xx	MH48xx	
		Rated Voltage		5±5%V	5-5%~12+5%V	
		Output Type		Line Driver		
	ations	Sink Current		20mA 26C31or equivalent		
	ecifica	Source Current				
	Electrical Specifications	Output Signal		$A, \overline{A}, B, \overline{B}, Z, \overline{Z}(\ U, \overline{U}, V, \overline{V}, W, \overline{W}\ )$		
	ctric	Output	VH	≧(Vcc	c-2V)	
	Ele	Voltage	VL	≦500	)mV	
		Current Consumption: 100mAMax.  Max. Response Frequency: 300kHz Max. Cable Diameter: 6.8mm  Output Phase Difference: Output phase difference 90 + zero pointsignal Cable Length: 1000±20mm  Cross Sectional Area: 0.18mm²  Signal Characteristic: RiseTime 100nsMax.; FallTime 100nsMax.				
	Mechanical Specifications	Max. Speed of Main Shaft: 6000rpm Starting Torque: 4.0 N-mm Typ. Moment of Inertia: 1.2 kg mm² Typ. Outer Diameter: 40.9mm Height: 26.7mm Weight: <85g Bore Diameter: 6mm /8mm Max. Shaft Load: Thrust: 15N /Radial: 30N (10 mm from mounting surface) Wire Color: DC +5V:Brown, 0V:Blue, A:Black, A:Black / Red, B: White Z: Orange, Z:Orange / Red, U: Yellow, U: Yellow/Red, V: Green, V: Green / Red, W: Pink, W: Pink / Red				
	nvironmental pecifications	Storage Shock: Vibration	Operating Temperature: -10°C~85°C, 95%RH (Non-condensing, Non-freezing Storage Temperature: -25°C~100°C (Non-condensing, Non-freezing) Shock: 100G's at6ms Vibration: 10 to 200Hz at 5G's Protection Degree: IP30			

# **Dimensions**

# Bore Diameter 6mm



## Bore Diameter 8mm



# Through Hole Shaft Outer Diameter 40.9mm

# MT4

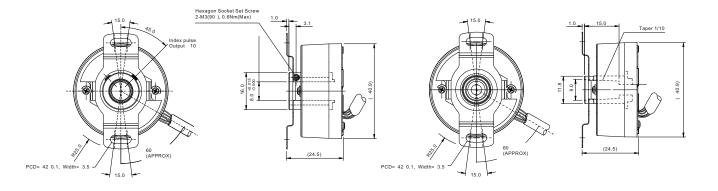


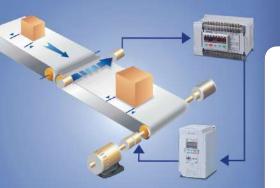
Series		MT4 Series			
	Model Name	MT45xx	MT48xx		
	Rated Voltag	5±5%V	5-5%~12+5%V		
	Output Type	Line	Line Driver		
v	Sink Curren	20mA 26C31or equivalent			
Electrical Specifications	Source Curre				
	Output Signa	$A, \overline{A}, B, \overline{B}, Z, \overline{Z} (\ U, \overline{U}, V, \overline{V}, W, \overline{W}\ )$			
	Output VH	≧(Vcc-2V)			
	Voltage <sub>VL</sub>	≦500mV			
	Current Consumption: 100mAMax.  Max. Response Frequency: 300kHz Max.  Cable Diameter: 6.8mm  Output Phase Difference: Output phase difference90 + zero pointsignal  Cable Length: 1000±20mm  Cross Sectional Area: 0.18mm²  Signal Characteristic: Rise Time 100ns Max.; Fall Time 100ns Max.				
Mechanical Specifications	Max. Speed of Main Shaft: 6000rpm Starting Torque: 4.0 N-mm Typ.  Moment of Inertia: 1.2 kg mm²Typ. Outer Diameter: 40.9mm Height: 26.7mm Weight: <85g Bore Diameter: 8mm /9mm (Taper 1/10) Max. Shaft Load: Thrust: 15N /Radial: 30N (10 mm from mounting surface) Wire Color: DC +5V: Brown, 0V: Blue, A: Black, A: Black / Red, B: White, B: White / Re  Z: Orange, Z: Orange / Red, U: Yellow, Ū: Yellow/ Red, V: Green, V: Green / Red, W: Pink, W: Pink / Red				
ocifications	Storage Tem Shock: 1000 Vibration: 10	Operating Temperature: -10°C~85°C, 95%RH (Non-condensing, Non-freezing) Storage Temperature: -25°C~100°C (Non-condensing, Non-freezing) Shock: 100G's at6ms Vibration: 10 to 200Hz at 5G's Protection Degree: IP30			

# **Dimensions**

## Bore Diameter 8mm

# Bore Diameter 9mm(Taper)





# Commutation Encoder (For Servo Motor)

# Incremental Encoder (For Spindle Applications)

# Through Hole Shaft Outer Diameter 43.7mm

# MT4



	Series			MT4 Series		
		Rated Voltage		5V±5%		
		Resolution		2500 PPR		
		Output Form		Line Driver		
		Consumption Current		100 mAMax.		
	Ö.	Sink Current		20mA		
	Electric Spec.	Output Signal		$A, \overline{A}, B, \overline{B}, Z, \overline{Z}(U, \overline{U}, V, \overline{V}, W, \overline{W})$		
	Ë	Output	VH	≧(Vin-2V)		
	le c	Voltage	VL	≦500mV		
		Current Consumption: 100mAMax. Max. Response Frequency: 300kHz Max. Cable Diameter: 6.8mm Output Phase Difference: Output phase difference 90 + zero point signal Cable Length: 1000±20mm Signal Characteristic: Rise Time 100ns Max. ; Fall Time 100ns Max.				
	Mechanical Specifications	Starting Momen Outer D Height: Weight Bore Di	t of Ine t of Ine Diamete 32.5mi : <85g ameter	Main Shaft: 6000rpm e: < 5.0 N-mmTyp. rtia: < 1.2kg mm²Typ. r: 43.7mm m : 8/9 mm ad: Thrust: 15N /Radial: 30N (10mm from mounting surface)		
Operating Temperature: -20°C~85°C, 95%RH without Storage Temperature: -25°C~100°C (Non-condensing Shock: 100G's at6ms Vibration: 10 to 200Hz at 5G's Protection Degree: IP40		e Temp 100G's on: 10 t	erature: -25°C~100°C (Non-condensing, Non-freezing) s at 6ms o 200Hz at 5G's			

# Solid Shaft Frame Size 68mm

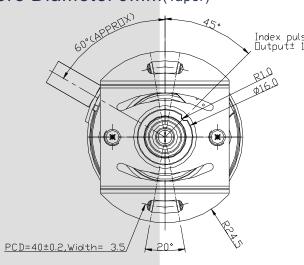


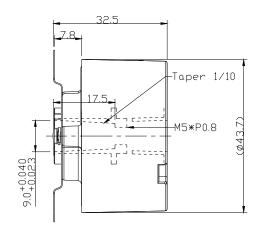


Series			CS Series		
Model Name		ame	CS75xx	CS79xx	
	Rated Voltage		5±5%V	5-5%~12+5%V	
	Output Type		Line Driver		
suc	Sink Current		20mA		
ficatio	Source Current				
Electrical Specifications	Output Signal		$A, \overline{A}, B, \overline{B}, Z, \overline{Z}$		
cal	Output	VH	≧(Vc	c-2V)	
ctri	Voltage	VL	≦50	0mV	
ш	Encoder Resolution: 1024 (PPR) Current Consumption: 100mAMax. Max. Response Frequency: 300kHz Max. Output Phase Difference: Output phase difference90 + zero point signal Signal Characteristic: Rise Time 500ns Typ.; Fall Time 500ns Typ.				
Mechanical Specifications	Max. Speed of Main Shaft: 8000rpm Starting Torque: 23 N-mm Typ. Moment of Inertia: 4.1kg mm² Typ. Frame size: 68mm Height: 102.8mm Weight: <420g Shaft Diameter: 15mm Max. Shaft Load: Thrust: 50N / Radial: 85N (10 mm from mounting surface) Pin Definition: Vcc: H, OV: K, A: A, A: N, B: C, B: R, Z: B, Z: P, Shielding: T				
Operating Temperature: -10°C~70°C, 95%RH (Non-condensing, Storage Temperature: -25°C~85°C (Non-condensing, Non-freezi Shock: 100G's at6ms Vibration: 10 to 200Hz at 5G's Protection Degree: Ip55					

# **Dimensions**

#### Bore Diameter 9mm(Taper)





# **Dimensions**

#### Shaft Diameter 15mm

